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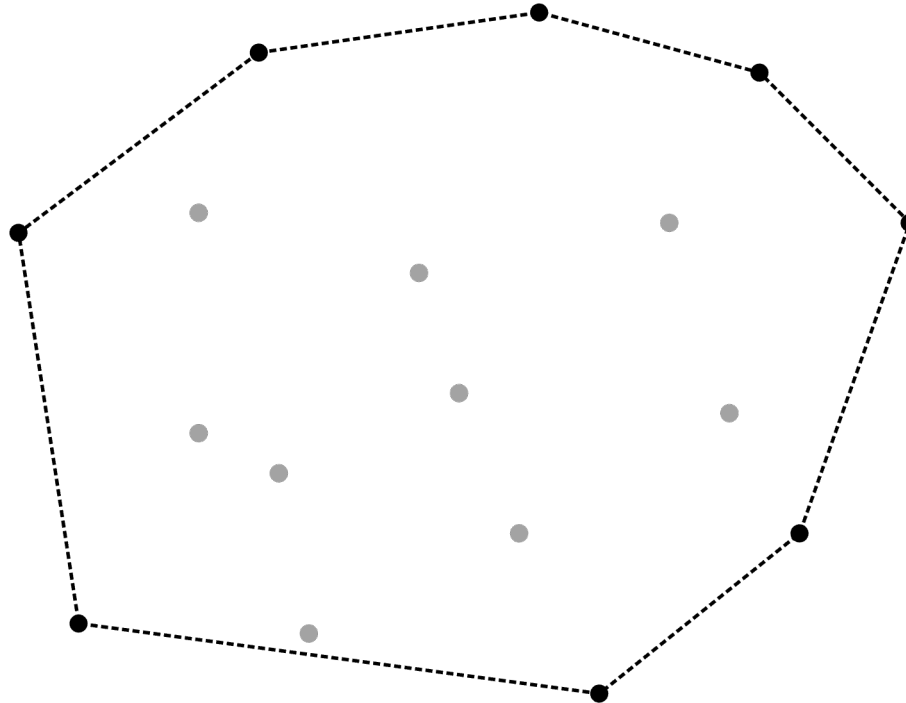


Computational Geometry – Exercise Meeting #3

December 8th, 2022

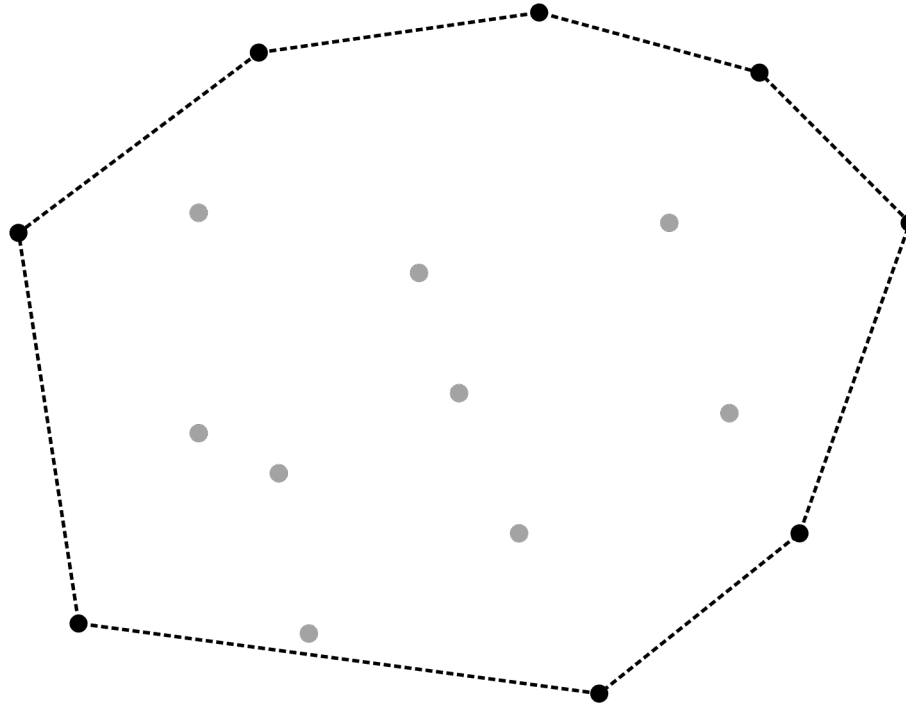
Farthest Pairs

$$O(n \log(n))$$

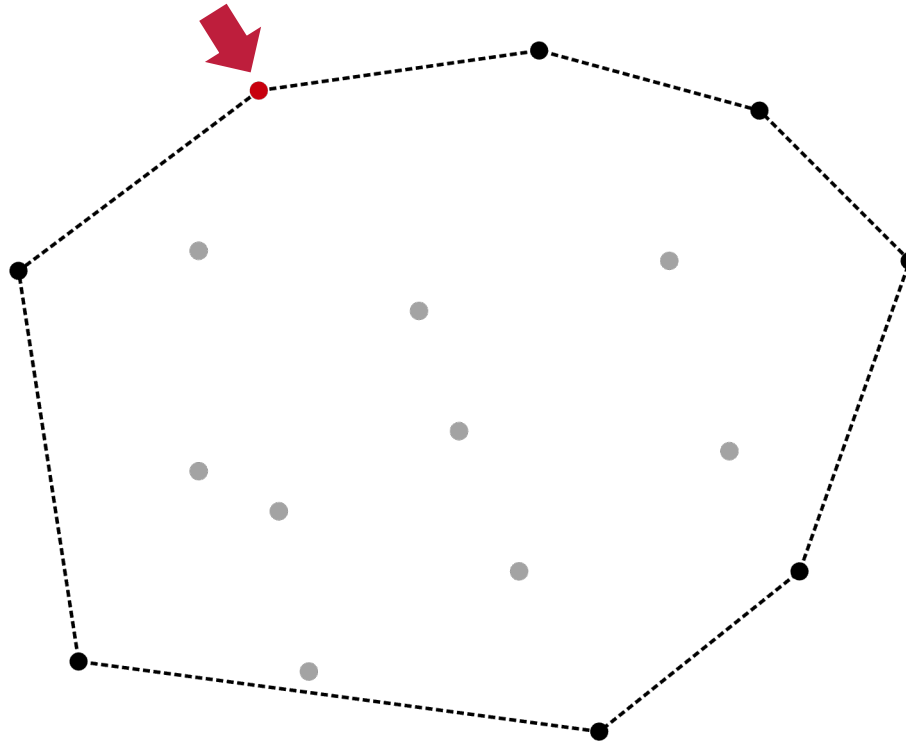


Farthest Pairs

$$O(n \log(n))$$

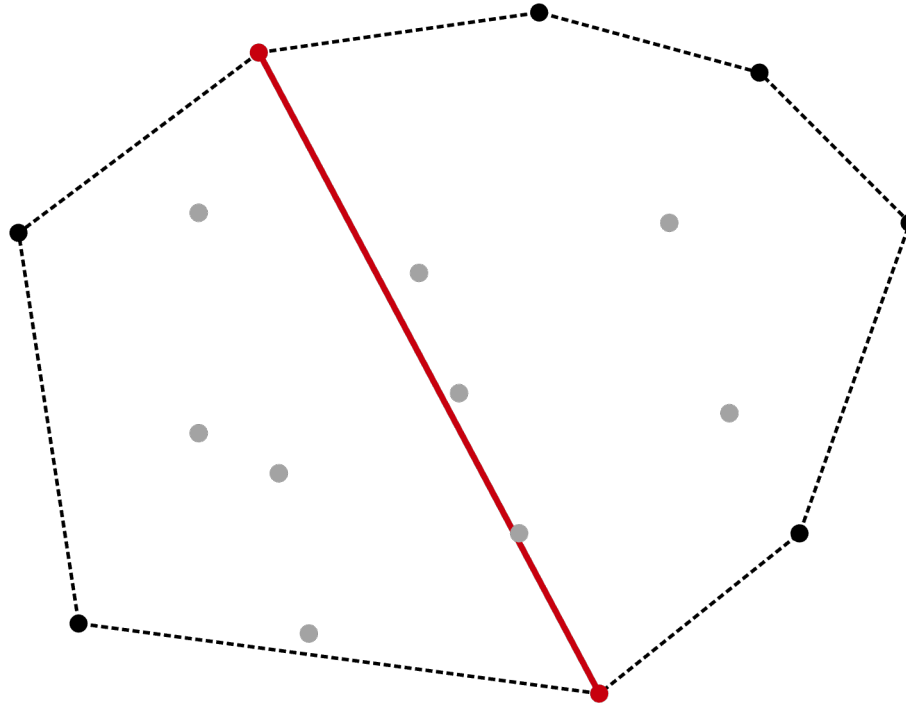


Farthest Pairs

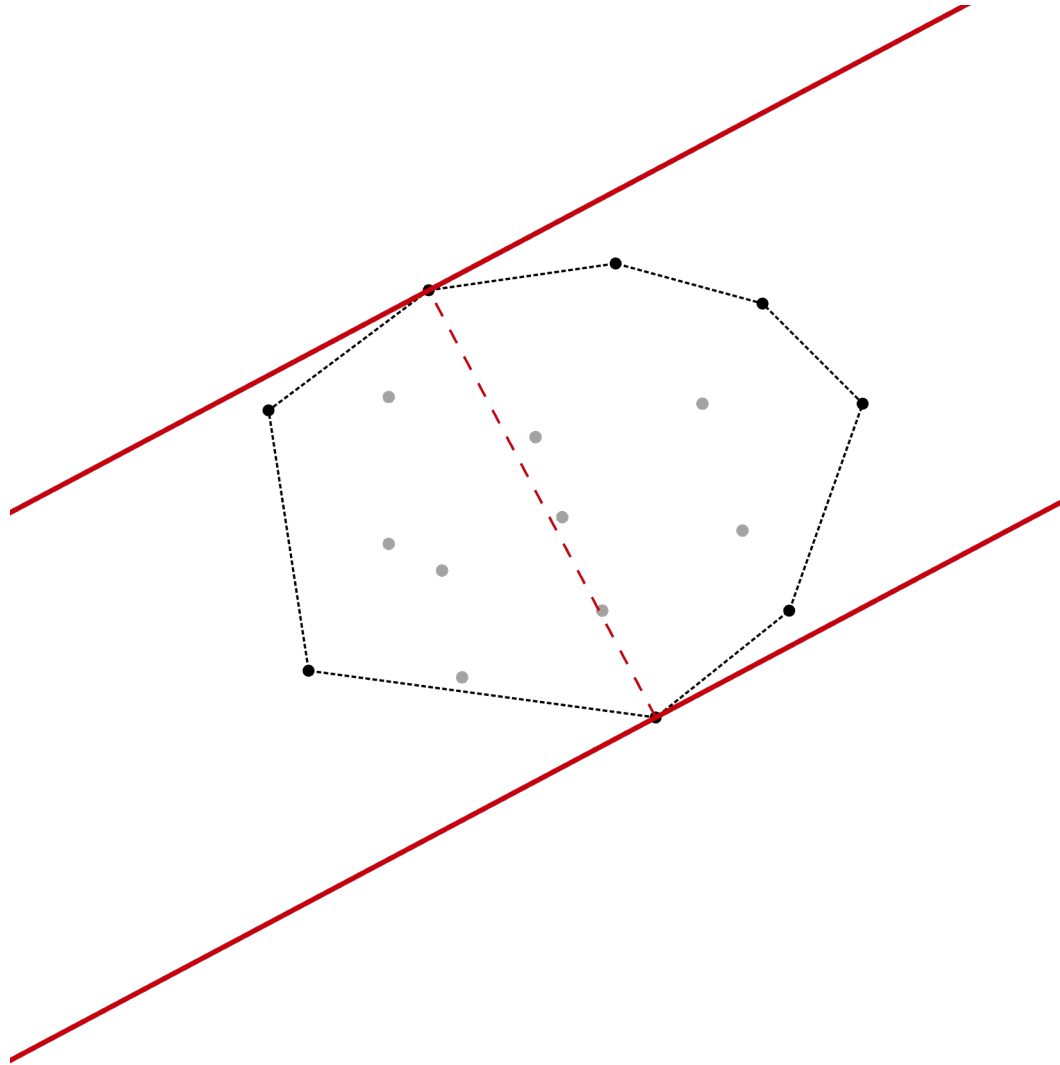


Farthest Pairs

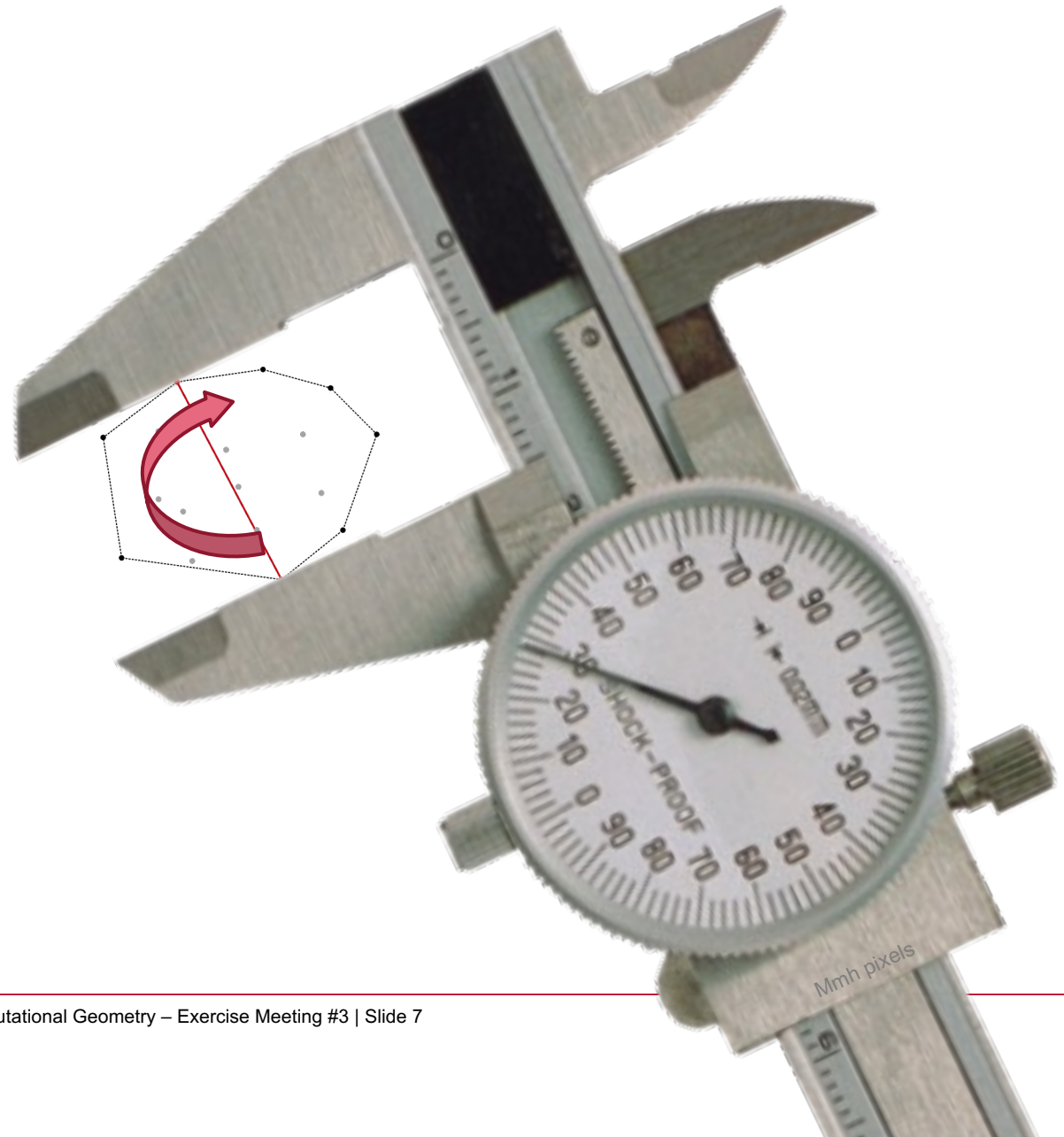
$O(n)$



Farthest Pairs



Farthest Pairs



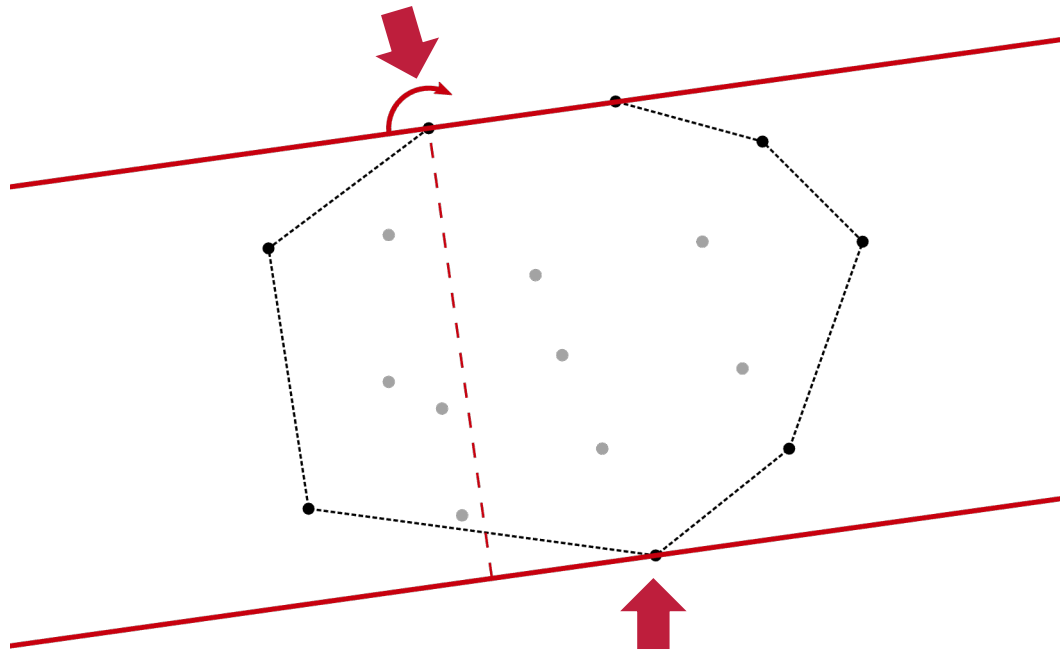
Source: www.richter-messzeuge.de



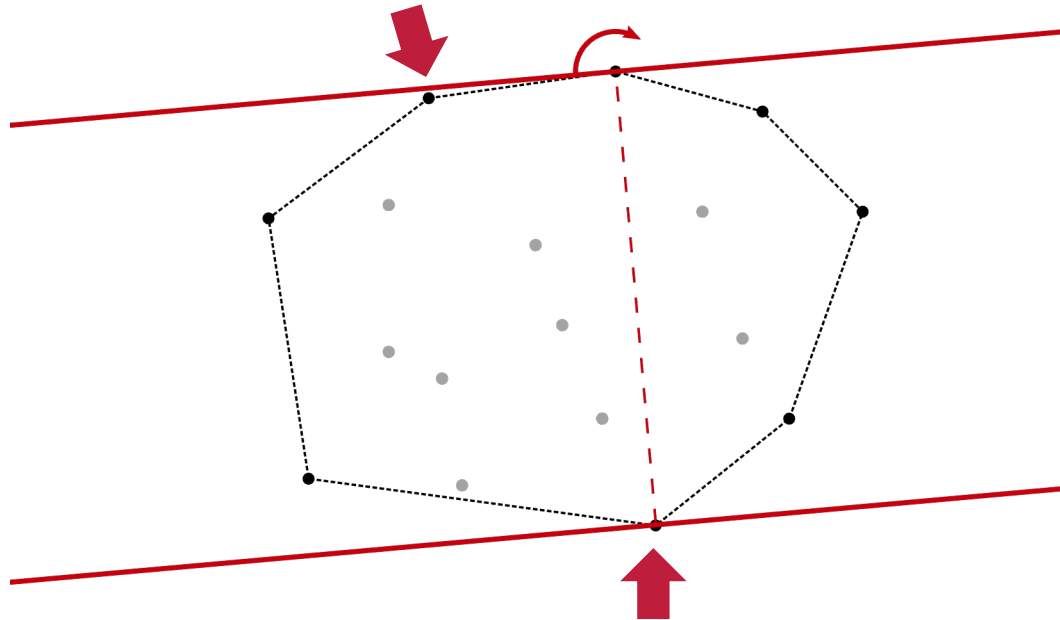
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December 8th, 2022 | Computational Geometry – Exercise Meeting #3 | Slide 7

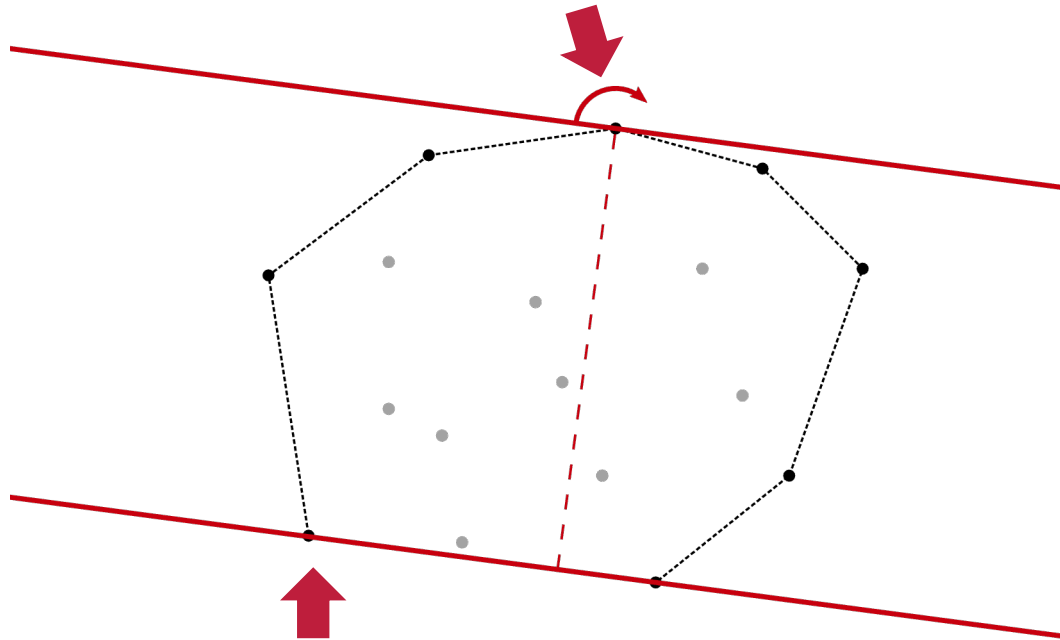
Farthest Pairs



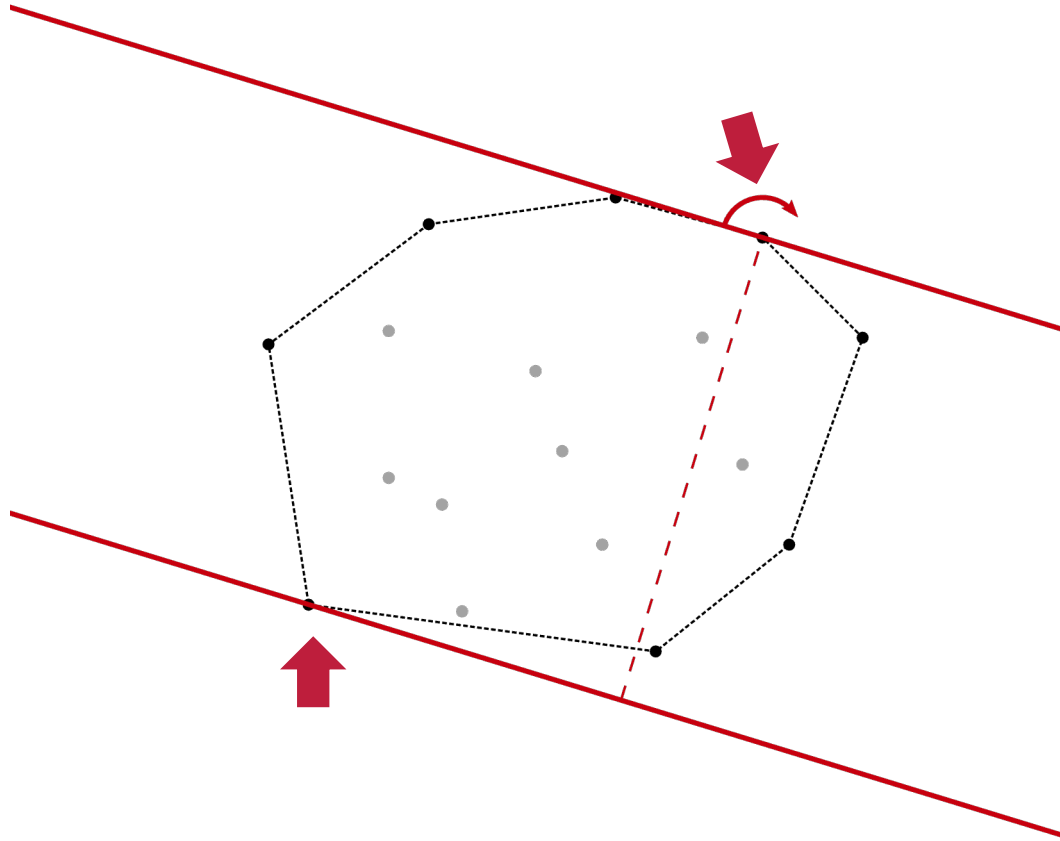
Farthest Pairs



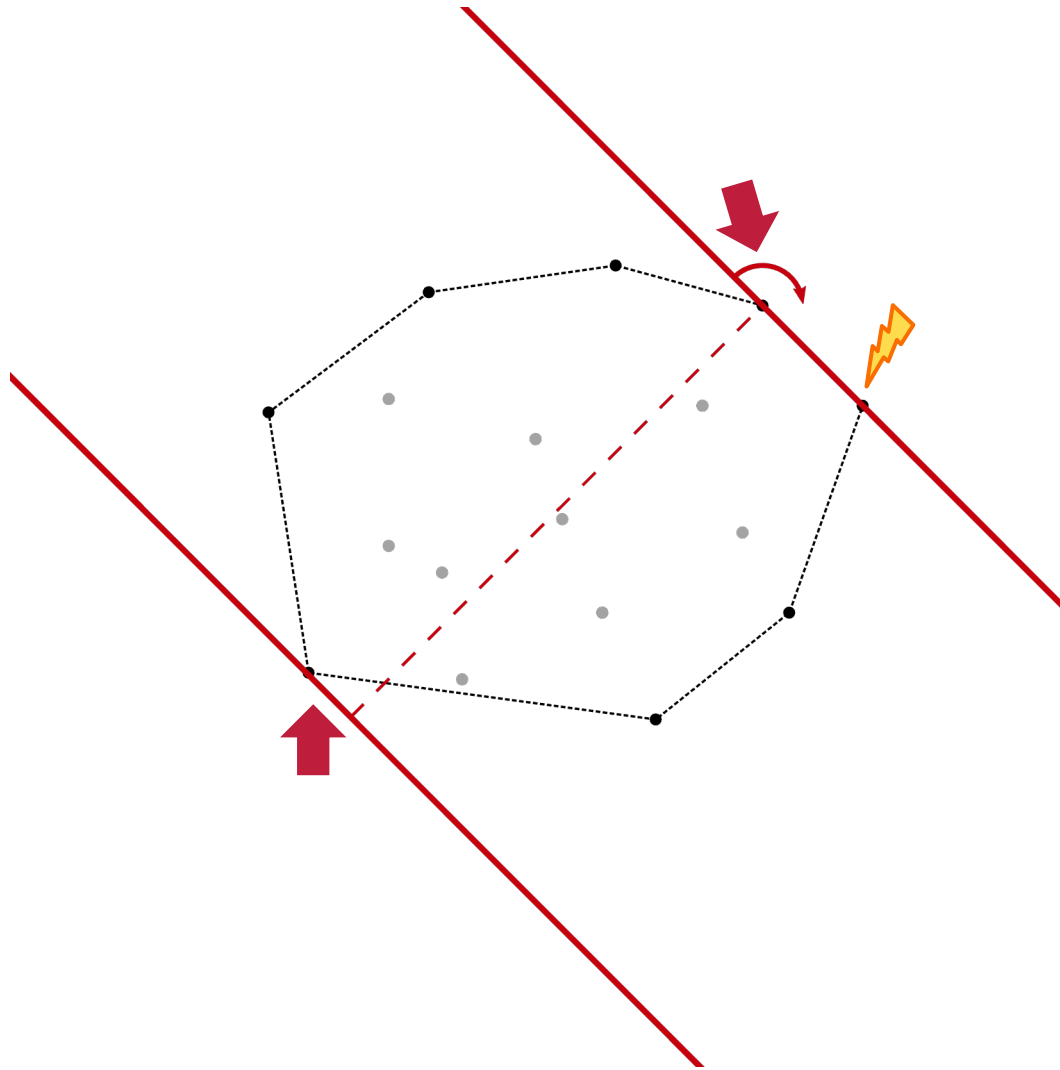
Farthest Pairs



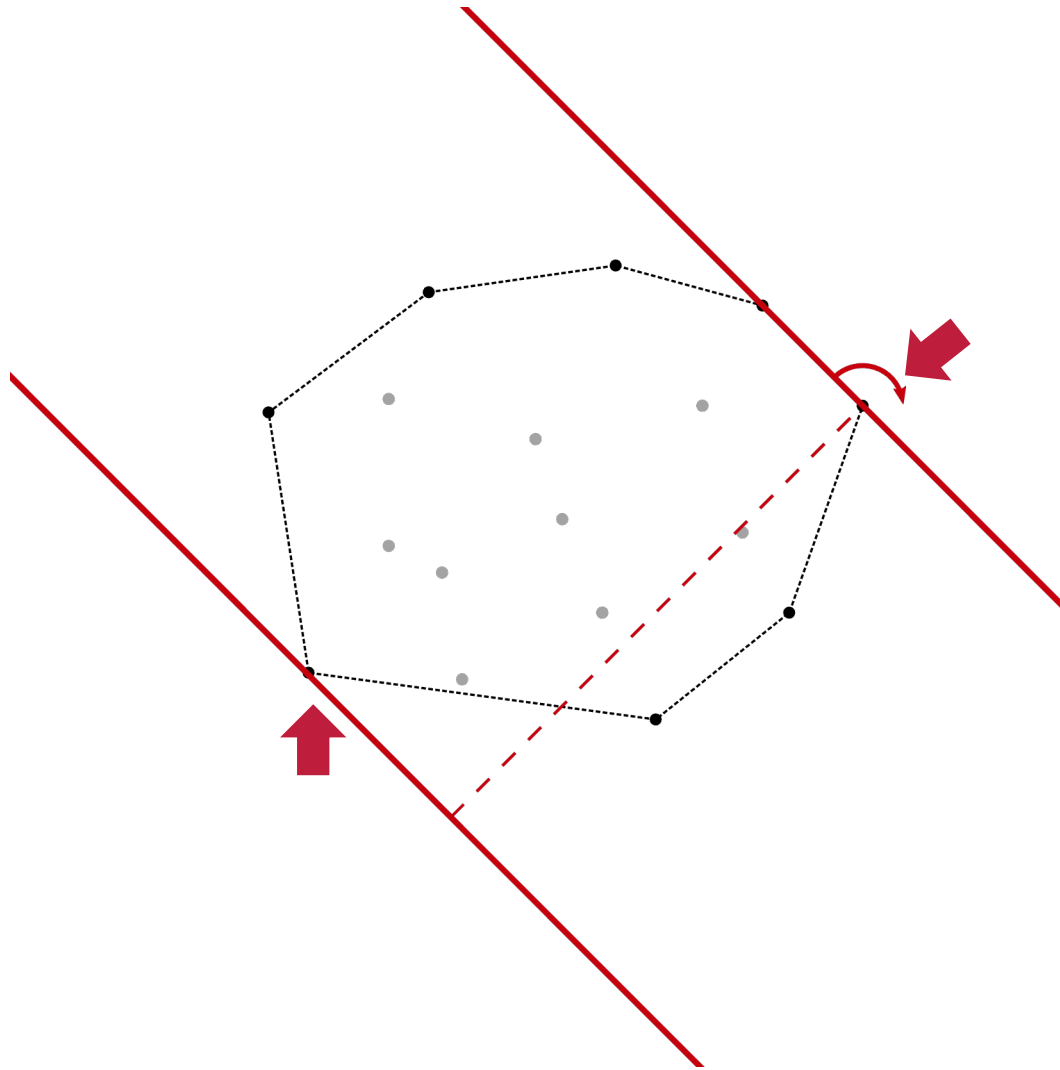
Farthest Pairs



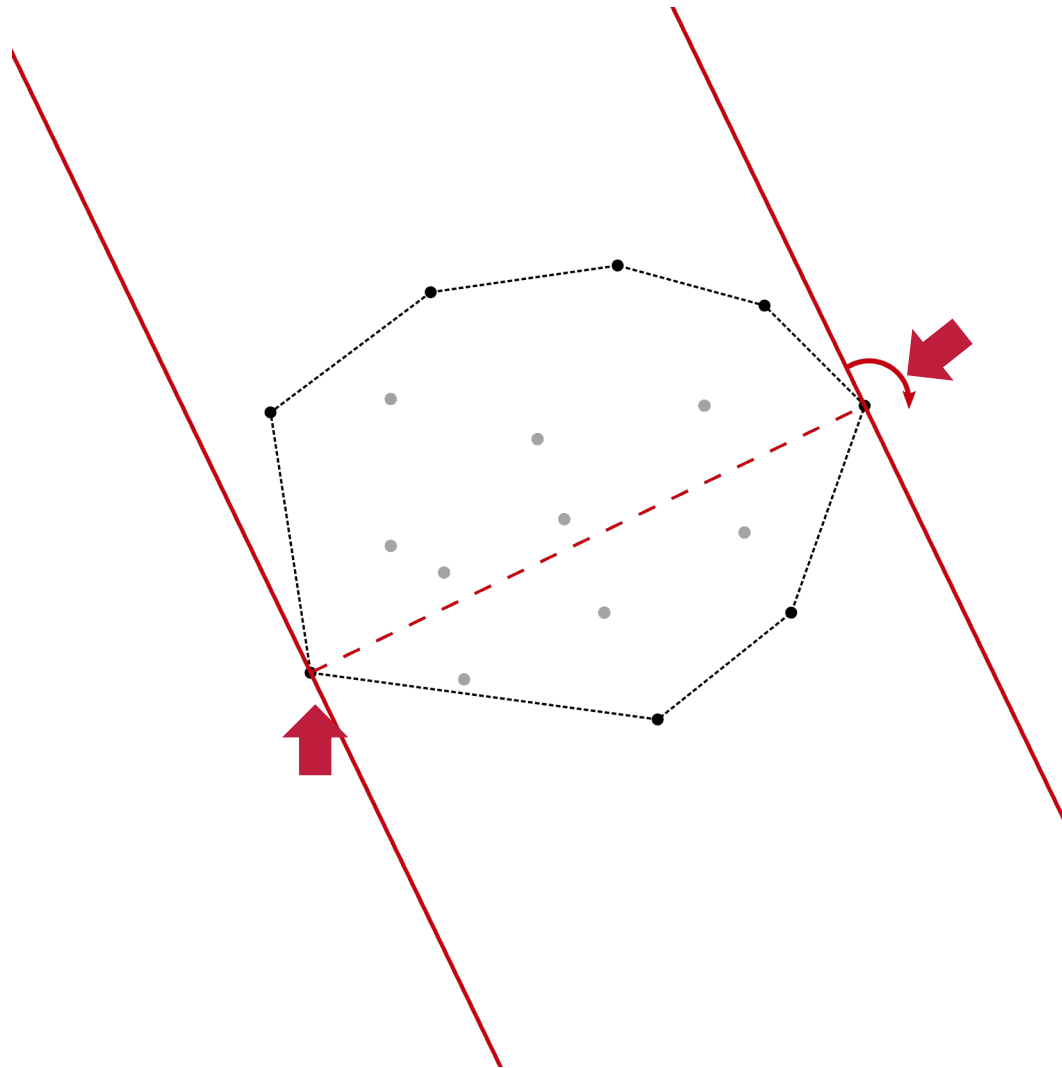
Farthest Pairs



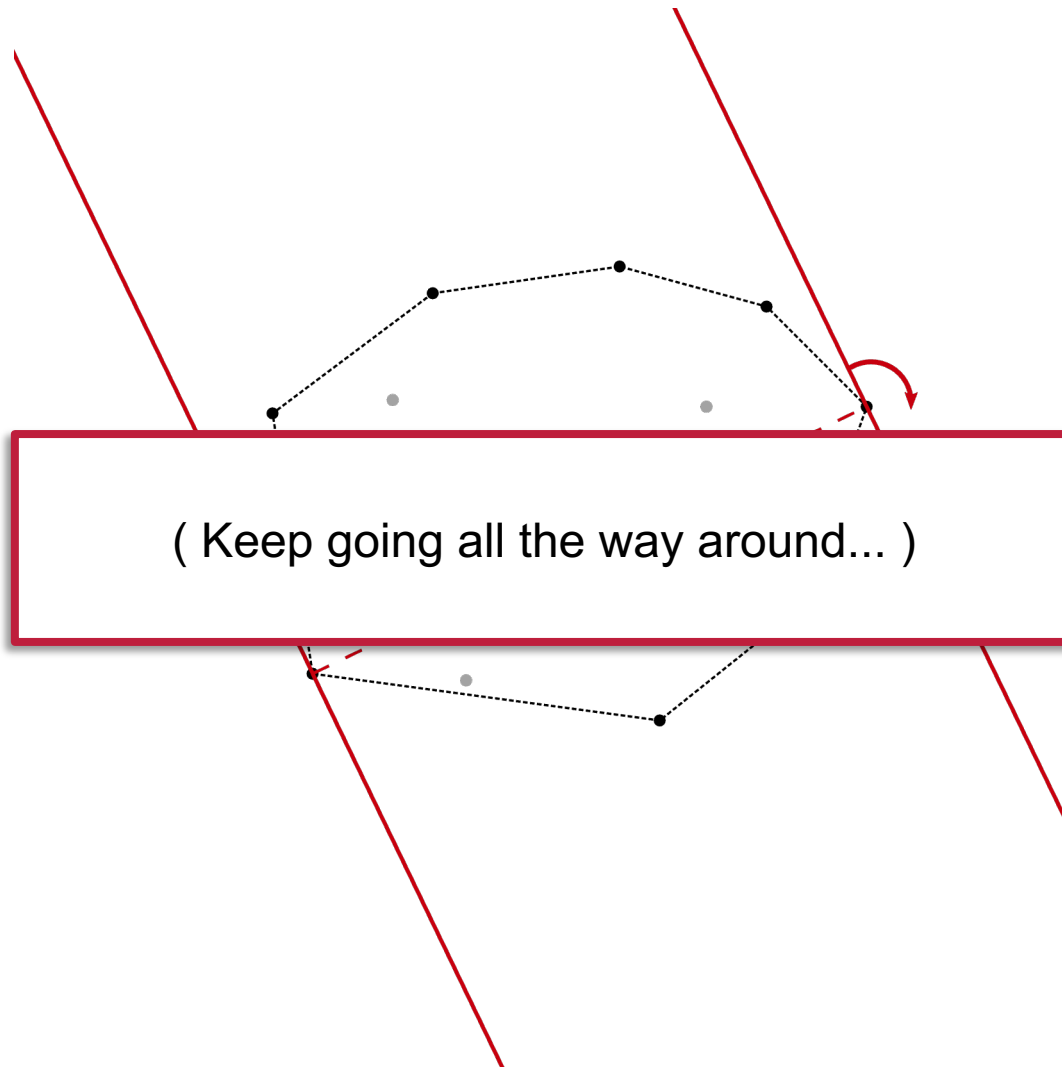
Farthest Pairs



Farthest Pairs

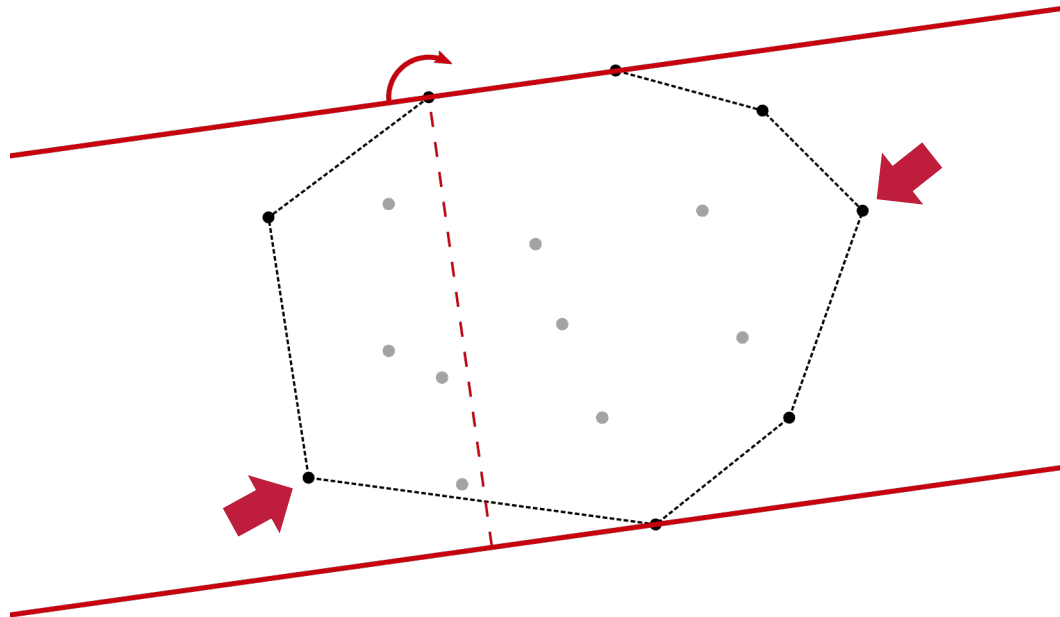


Farthest Pairs



Farthest Pairs

$O(n \log(n))$ total



Rotating Calipers

```
/* p[] is in standard form, ie, counter clockwise order,
   distinct vertices, no collinear vertices.
   ANGLE(m, n) is a procedure that returns the clockwise angle
   swept out by a ray as it rotates from a position parallel
   to the directed segment Pm,Pm+1 to a position parallel
   to Pn, Pn+1
   We assume all indices are reduced to mod N (so that N+1 = 1).
*/
GetAllAntiPodalPairs(p[1..n])
  // Find first anti-podal pair by locating vertex opposite P1
  i = 1
  j = 2
  while angle(i, j) < pi
    j++
  yield i, j

  /* Now proceed around the polygon taking account of
     possibly parallel edges. Line L passes through
     Pi, Pi+1 and M passes through Pj, Pj+1
  */

  // Loop on j until all of P has been scanned
  current = i
  while j != n
    if angle(current, i + 1) <= angle(current, j + 1)
      j++
      current = j
    else
      i++
      current = i
  yield i, j
```

Rotating Calipers – Other Applications

Distances [\[edit \]](#)

- Diameter (maximum width) of a convex polygon^{[6][7]}
- Width (minimum width) of a convex polygon^[8]
- Maximum distance between two convex polygons^{[9][10]}
- Minimum distance between two convex polygons^{[11][12]}
- Widest empty (or separating) strip between two convex polygons (a simplified low-dimensional variant of a problem arising in support vector machine based machine learning)
- Grenander distance between two convex polygons^[13]
- Optimal strip separation (used in medical imaging and solid modeling)^[14]

Bounding boxes [\[edit \]](#)

- Minimum area oriented bounding box
- Minimum perimeter oriented bounding box

Triangulations [\[edit \]](#)

- Onion triangulations
- Spiral triangulations
- Quadrangulation
- Nice triangulation
- Art gallery problem
- Wedge placement optimization problem^[15]

Multi-polygon operations [\[edit \]](#)

- Union of two convex polygons
- Common tangents to two convex polygons
- Intersection of two convex polygons^[16]
- Critical support lines of two convex polygons
- Vector sums (or Minkowski sum) of two convex polygons^[17]
- Convex hull of two convex polygons

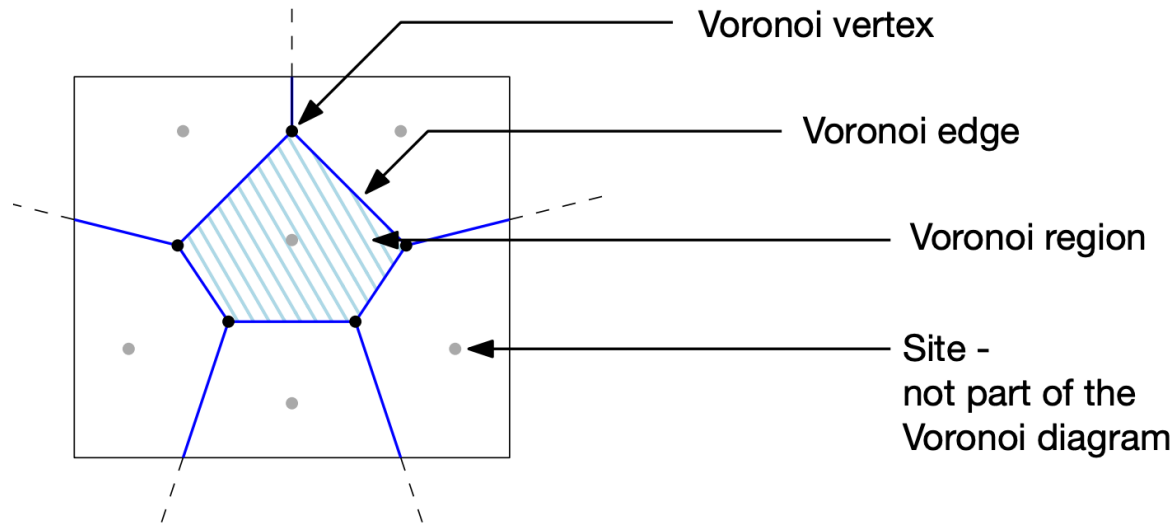
Traversals [\[edit \]](#)

- Shortest transversals^{[18][19]}
- Thinnest-strip transversals^[20]

Others [\[edit \]](#)

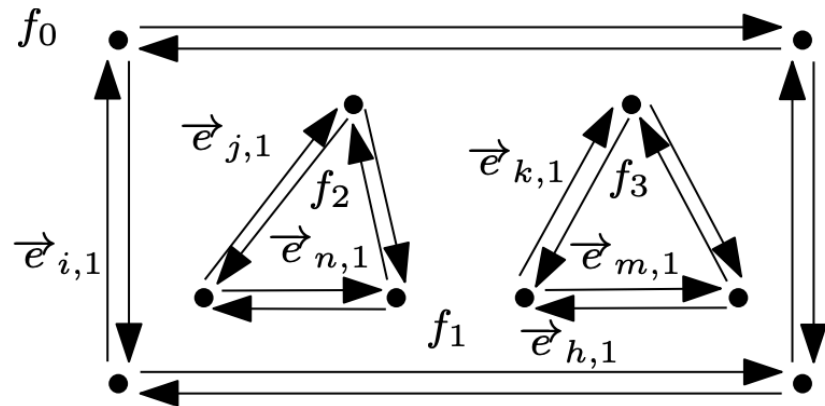
- Non parametric decision rules for machine learned classification^[21]
- Aperture angle optimizations for visibility problems in computer vision^[22]
- Finding longest cells in millions of biological cells^[23]
- Comparing precision of two people at firing range
- Classify sections of brain from scan images

Voronoi Basics



Theorem 4.7

$Vor(\mathcal{P})$ has precisely n Voronoi regions, at most $2n - 5$ Voronoi vertices and at most $3n - 6$ Voronoi edges.





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EU-KOMMISSIONSCHEFIN

Wolf tötet Ursula von der Leyens Pony – jetzt will sie den geschützten Tieren an den Kragen

ERGEBNIS DES GENTESTS

Problemwolf GW 950m hat von der Leyens Pony „Dolly“ gerissen



User:Mas3cf, CC BY-SA 4.0,
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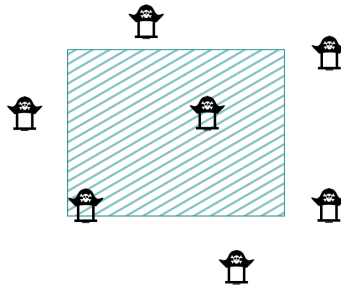


URSULAVONDERLEYEN/INSTAGRAM



Maximizing distance to sites in a bounded area

Provided a set of **sites** P in the plane and an axis-aligned **rectangle** R , find a point inside of R with **maximal distance to the nearest member of P** . Assume that no three points in P are collinear.



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